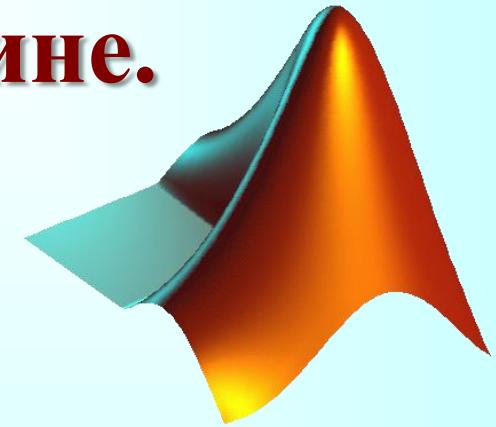
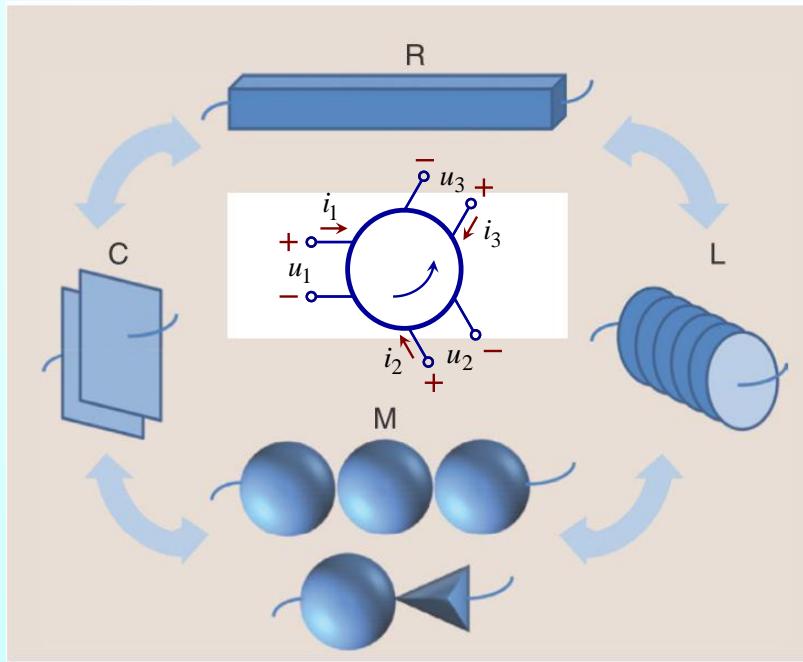


# Практикум из рачунарске анализе кола

## 2. Операциони појачавач. Алгебарске једначине.



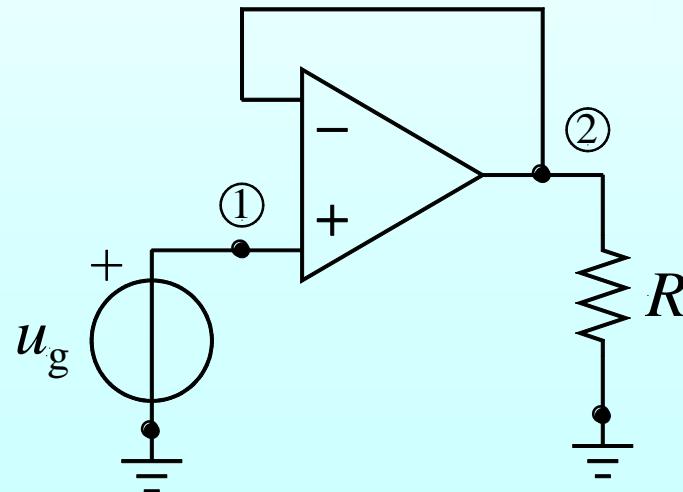
Милка Потребић Иваниш  
Никола Баста

# Рачунарски (софтверски) алати

- *Mathematica*, WolframAlpha, MuPAD, Maxima, SymPy, SymPy Live, SymPy Gamma
- MATLAB, Scilab, Octave, FreeMat, Julia
- LTspice, QucsStudio, ngspice, Xyce, XCircuit
- Python, MathCAD, MAPLE, GeoGebra
- Symbolab, SpeQ Mathematics, meta-calculator, Desmos, ...

# Пратилац напона

Одредити напонско појачање кола са слике, које се назива пратилац напона (voltage follower).



# SymPy Live

Symbolic Python Live, <http://live.sympy.org/>

The screenshot shows a Mozilla Firefox browser window titled "SymPy Live - Mozilla Firefox". The main content area is a "Python console for SymPy 0.7.1 (Python 2.5.2)". The console displays the following Python code and its output:

```
Python console for SymPy 0.7.1 (Python 2.5.2)

These commands were executed:
>>> from __future__ import division
>>> from sympy import *
>>> x, y, z, t = symbols('x y z t')
>>> k, m, n = symbols('k m n', integer=True)
>>> f, g, h = symbols('f g h', cls=Function)

Documentation can be found at http://docs.sympy.org/.

>>> # Pratilac napona (voltage follower)
... var('iug, iR, i1OP, i2OP, ug, uR, uiOP, u2OP, R')
... jednacine = [
... Eq(iug + i1OP, 0), Eq(i2OP - i1OP + iR, 0),
... Eq(ug - uiOP - u2OP, 0), Eq(u2OP - uR, 0),
... Eq(uiOP, 0), Eq(i1OP, 0), Eq(uR - R*iR, 0)
... ]
... promenljive = [
... iug, iR, i1OP, i2OP, uR, uiOP, u2OP
... ]
>>> odziv = solve(jednacine, promenljive)
>>> odziv
{ i1OP : 0, i2OP : - ug / R, iR : ug / R, iug : 0, uiOP : 0, u2OP : ug, uR : ug }

>>> pojacanje = (uR/ug).subs(odziv)
>>> pojacanje
```

A small number "1" is displayed in a box above the console output. At the bottom of the console window, there is a toolbar with buttons for "Evaluate", "Clear", and "Fullscreen".

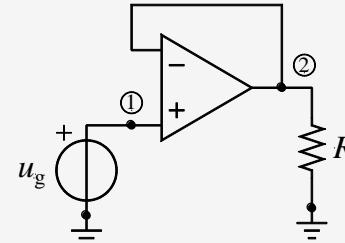
## SymPy Live

```
Python console for SymPy 0.7.1 (Python 2.5.2)

These commands were executed:
>>> from __future__ import division
>>> from sympy import *
>>> x, y, z, t = symbols('x y z t')
>>> k, m, n = symbols('k m n', integer=True)
>>> f, g, h = symbols('f g h', cls=Function)

Documentation can be found at http://docs.sympy.org/.

>>> # Pratilac napona (voltage follower)
... var('iug, iR, i1OP, i2OP, ug, uR, u1OP, u2OP, R')
... jednacine = [
... Eq(iug + i1OP, 0), Eq(i2OP - i1OP + iR, 0),
... Eq(ug - u1OP - u2OP, 0), Eq(u2OP - uR, 0),
... Eq(u1OP, 0), Eq(i1OP, 0), Eq(uR - R*iR, 0)
... ]
... promenljive = [
... iug, iR, i1OP, i2OP, ug, uR, u1OP, u2OP
... ]
>>> odziv = solve(jednacine, promenljive)
>>> odziv
{ i1OP : 0, i2OP : - ug / R, iR : ug / R, iug : 0, u1OP : 0, u2OP : ug, uR : ug }
```



```
>>> pojacanje = (uR/ug).subs(odziv)
>>> pojacanje
```

1

Notepad++, <http://notepad-plus-plus.org/>

```
D:\eKola\Zbirka\Aлатива3 Pratilac\PratilacNapona.py - Notepad++
File Edit Search View Encoding Language Settings Macro Run Plugins Window ?
PratilacNapona.py
1 # Pratilac napona (voltage follower)
2 var('iug, iR, i1OP, i2OP, ug, uR, u1OP, u2OP, R')
3 jednacine = [
4 Eq(iug + i1OP, 0), Eq(i2OP - i1OP + iR, 0),
5 Eq(ug - u1OP - u2OP, 0), Eq(u2OP - uR, 0),
6 Eq(u1OP, 0), Eq(i1OP, 0), Eq(uR - R*iR, 0)
7 ]
8 promenljive = [
9 iug, iR, i1OP, i2OP, ug, uR, u1OP, u2OP
10 ]
11 odziv = solve(jednacine, promenljive)
12 pojacanje = (uR/ug).subs(odziv)
```

# MATLAB: Symbolic Math Toolbox

```
clear variables

syms iug iR i1OP i2OP ug uR u1OP u2OP R
promenljive = [iug, iR, i1OP, i2OP, ug, uR, u1OP, u2OP]

promenljive = (iug iR i1OP i2OP ug uR u1OP u2OP)

jednacine = [iug + i1OP == 0, i2OP-i1OP+iR == 0, ug-u1OP-u2OP == 0, ...
    u2OP - uR ==0, u1OP == 0, i1OP == 0, uR == R*iR]

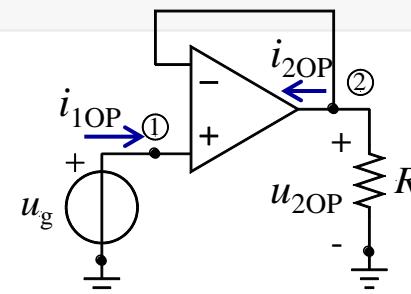
jednacine = (i1OP + iug = 0 i2OP - i1OP + iR = 0 ug - u2OP - u1OP = 0 u2OP - uR = 0 u1OP = 0 i1OP = 0 uR = R iR)
```

```
odziv = solve(jednacine, promenljive)
```

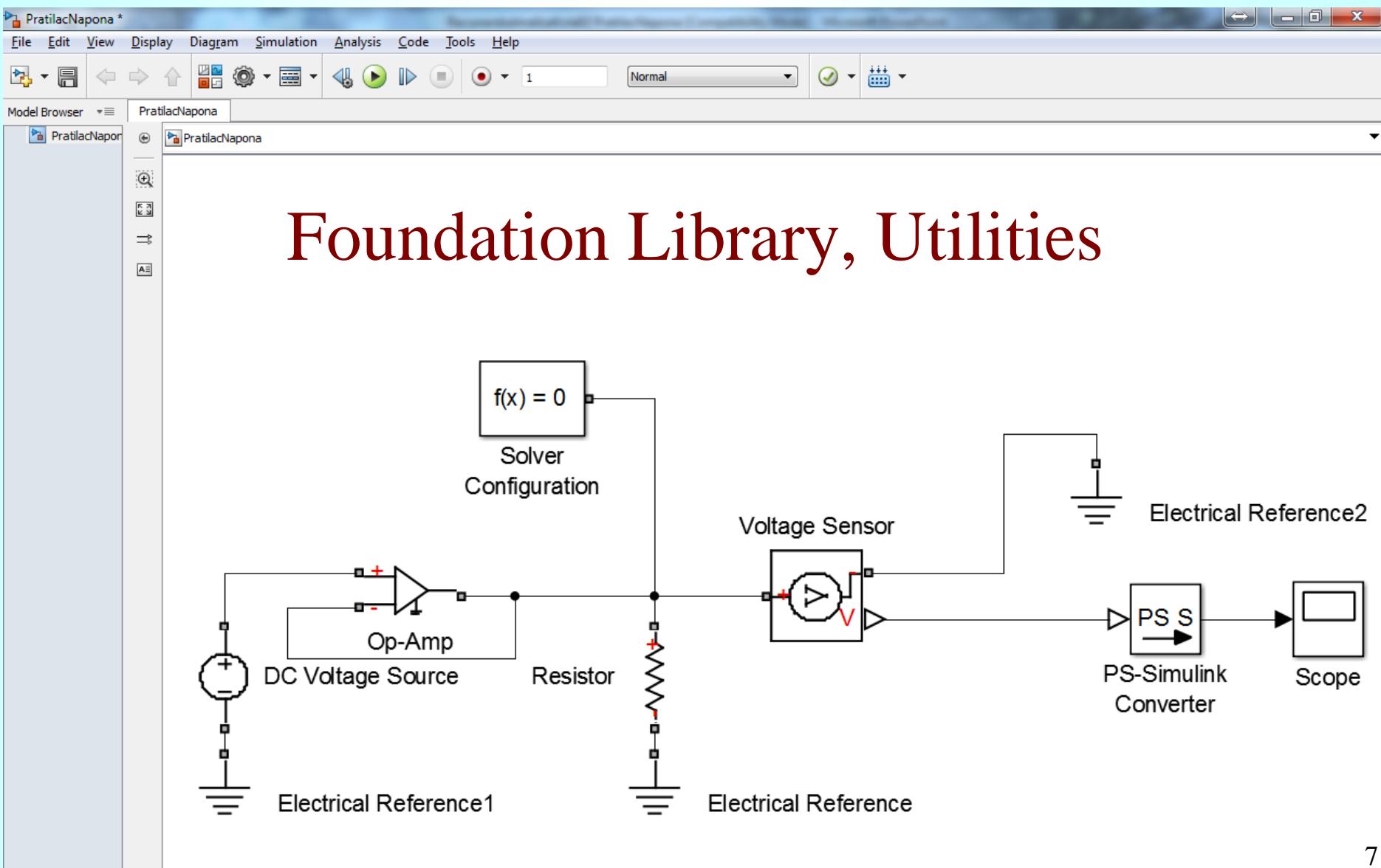
```
odziv = struct with fields:
  iug: 0
  iR: ug/R
  i1OP: 0
  i2OP: -ug/R
  ug: ug
  u1OP: 0
  u2OP: ug
```

```
pojacanje = odziv.u2OP / ug
```

```
pojacanje = |
```



# MATLAB: Simscape



# MATLAB: Simscape

## Foundation Library, Utilities

The screenshot illustrates the MATLAB Simscape Foundation Library Utilities environment. It features three main windows:

- Circuit Diagram Window:** Shows a circuit model with a DC Voltage Source, Op-Amp, Resistor, and various Simscape blocks like f(x) = 0, Solver Configuration, Voltage Sensor, Electrical Reference, PS-Simulink Converter, and Scope.
- Block Parameters: DC Voltage Source Dialog:** Displays the parameters for the DC Voltage Source block. The "Constant voltage:" field is set to 1 V. The "OK", "Cancel", "Help", and "Apply" buttons are visible at the bottom.
- Block Parameters: Resistor Dialog:** Displays the parameters for the Resistor block. The "Resistance:" field is set to 1000 Ohm. The "OK", "Cancel", "Help", and "Apply" buttons are visible at the bottom.
- Scope Window:** Shows a plot of a constant voltage signal over time, with the y-axis ranging from 0 to 2 and the x-axis from 0 to 1. The signal value is 1.0.

# Maxima

Maxima: <http://maxima.sourceforge.net/>

wxMaxima: <http://andrejv.github.com/wxmaxima/index.html>

CESGA Maxima on line: <http://maxima.cesga.es/>

wxMaxima 12.01.0 [ PratilacNapona.wxm ]

File Edit Cell Maxima Equations Algebra Calculus Simplify Plot Numeric Help

Pratilac napona (voltage follower)

Figure 1:

```
(%i1) jednacine: [iug + i1OP = 0, i2OP - i1OP + iR = 0,
 ug - u1OP - u2OP = 0, u2OP - uR = 0,
 u1OP = 0, i1OP = 0, uR = R*iR];
(%o1) [i1OP+iug=0,iR+i2OP-i1OP=0,-u2OP-u1OP+ug=0,u2OP-uR
=0,u1OP=0,i1OP=0,uR=iR R]
(%i2) odziv: linsolve(jednacine,
 [iug, iR, i1OP, i2OP, uR, u1OP, u2OP]);
(%o2) [iug=0,iR=ug/R,i1OP=0,i2OP=-ug/R,uR=ug,u1OP=0,u2OP=ug]
(%i3) pojacanje: uR/ug, odziv;
(%o3) 1
```

Ready for user input

# Инструментациони појачавач

- Одредити напон  $v_3$  отпорника  $R_8$ ?
- Нацртати график напона  $v_3$  отпорника  $R_8$  у функцији времена?
- Колика је снага извора?

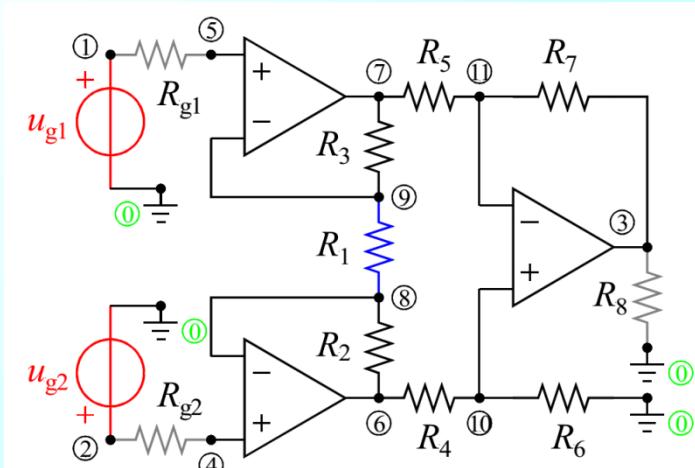
Вредности елемената су познате:

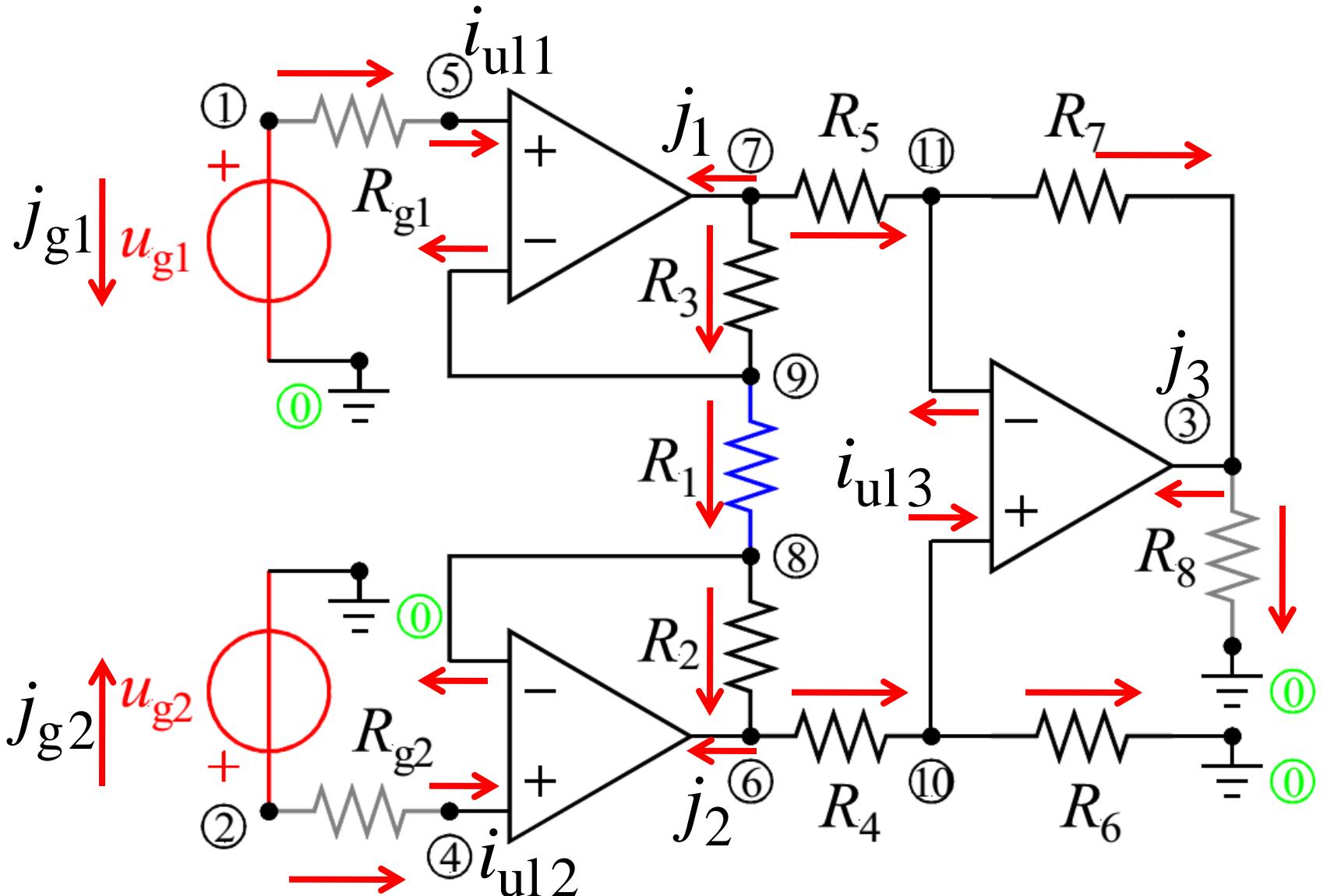
$$R_2 = R_3 = R_4 = R_5 = R_6 = R_7 = R_8 = R$$

$$R = 1 \text{ k}\Omega, R_1 = 2 \text{ k}\Omega, R_{g1} = R_{g2} = 1 \text{ k}\Omega$$

$$u_{g1}(t) = U h(t), u_{g2}(t) = U h(t-T)$$

$$U = 10 \text{ V}, T = 1 \text{ s}$$





# Модификована метода потенцијала чврова

$$(1) j_{g1} + (V_1 - V_5)/R_{g1} = 0$$

$$(2) j_{g2} + (V_2 - V_4)/R_{g2} = 0$$

$$(3) j_3 - (V_{11} - V_3)/R_7 + V_3/R_8 = 0$$

$$(4) -(V_2 - V_4)/R_{g2} + i_{ul2} = 0$$

$$(5) -(V_1 - V_5)/R_{g1} + i_{ull} = 0$$

$$(6) j_2 + (V_6 - V_{10})/R_4 - (V_8 - V_6)/R_2 = 0$$

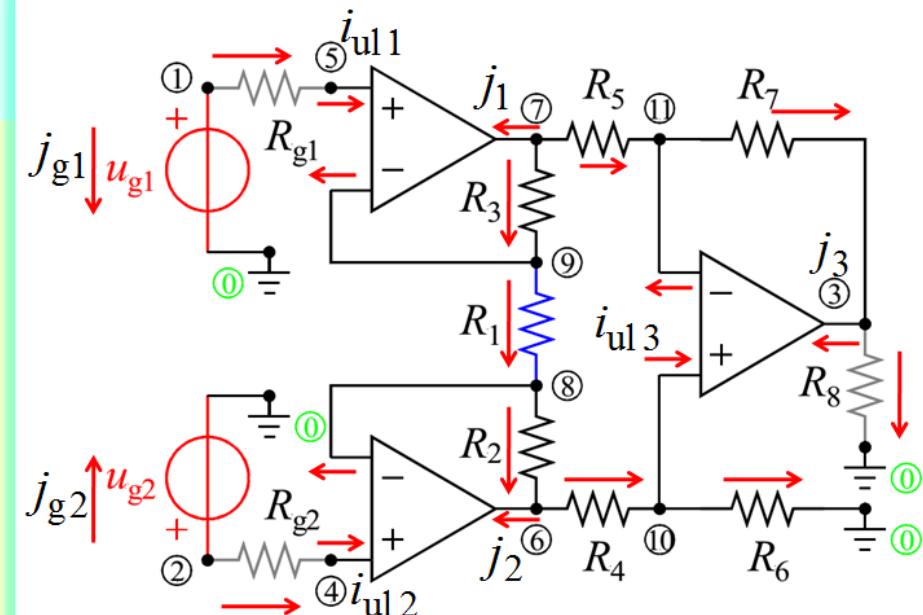
$$(7) j_1 + (V_7 - V_9)/R_3 + (V_7 - V_{11})/R_5 = 0$$

$$(8) -i_{ul2} - (V_9 - V_8)/R_1 + (V_8 - V_6)/R_2 = 0$$

$$(9) -i_{ull} - (V_7 - V_9)/R_3 + (V_9 - V_8)/R_1 = 0$$

$$(10) -(V_6 - V_{10})/R_4 + i_{ul3} + V_{10}/R_6 = 0$$

$$(11) -(V_7 - V_{11})/R_5 - i_{ul3} + (V_{11} - V_3)/R_7 = 0$$



$$i_{ull} = 0$$

$$i_{ul2} = 0$$

$$i_{ul3} = 0$$

$$V_5 = V_9$$

$$V_4 = V_8$$

$$V_{10} = V_{11}$$

$$V_1 = u_{g1}$$

$$V_2 = u_{g2}$$

# MATLAB: Symbolic Math Toolbox

## Променљиве, једначине, решавање

```
clear variables
```

```
syms R R1 R2 R3 R4 R5 R6 R7 R8 Rg1 Rg2 iul1 iul2 iul3 j1 j2 j3 jg1 jg2 ug1 ug2 v1 v10 v11 v2 v3 v4 v5 v6 v7 v8 v9
jednacine = [jg1 + (v1 - v5)/Rg1 == 0, ...
             v1 == ug1, jg2 + (v2 - v4)/Rg2 == 0, ...
             v2 == ug2, j3 + v3/R8 - (v11 - v3)/R7 == 0, ...
             -((v2 - v4)/Rg2) + iul2 == 0, -((v1 - v5)/Rg1) + iul1 == 0, ...
             j2 + (v6 - v10)/R4 - (v8 - v6)/R2 == 0, j1 + (v7 - v11)/R5 + (v7 - v9)/R3 == 0, ...
             -iul2 - (v9 - v8)/R1 + (v8 - v6)/R2 == 0, -iul1 - (v7 - v9)/R3 + (v9 - v8)/R1 == 0, ...
             -((v6 - v10)/R4) + v10/R6 + iul3 == 0, -((v7 - v11)/R5) + (v11 - v3)/R7 - iul3 == 0, ...
             iul1 == 0, iul2 == 0, iul3 == 0, ...
             v5 == v9, v4 == v8, v10 == v11]
```

syms

sym

jednacine =

$$\left( jg_1 + \frac{v_1 - v_5}{Rg_1} = 0 \quad v_1 = ug_1 \quad jg_2 + \frac{v_2 - v_4}{Rg_2} = 0 \quad v_2 = ug_2 \quad j_3 + \frac{v_3 - v_{11}}{R_8} = 0 \quad iul_2 - \frac{v_2 - v_4}{Rg_2} = 0 \quad iul_1 - \frac{v_1 - v_5}{Rg_1} = 0 \quad j_2 + \frac{v_6 - v_8}{R_2} + \frac{v_6 - v_{10}}{R_4} = 0 \right)$$

assume

```
assume(0 < Rg1 & 0 < Rg2 & 0 < R1 & 0 < R2 & 0 < R3 & 0 < R4 & 0 < R5 & 0 < R6 & 0 < R7 & 0 < R8 & 0 < R)
```

```
promenljive = [v1, v2, v3, v4, v5, v6, v7, v8, v9, v10, v11, j1, j2, j3, iul1, iul2, iul3, jg1, jg2]
```

```
promenljive = (v1 v2 v3 v4 v5 v6 v7 v8 v9 v10 v11 j1 j2 j3 iul1 iul2 iul3 jg1 jg2)
```

```
odziv = solve(jednacine, promenljive)
```

solve

```
odziv = struct with fields:
```

```
v1: ug1
```

```
v2: ug2
```

```
v3: -(R1*R4*R7*ug1 - R1*R5*R6*ug2 + R2*R5*R6*ug1 + R1*R6*R7*ug1 - R2*R5*R6*ug2 + R3*R4*R7*
```

```
v4: ug2
```

# Замена променљивих и вредности

```
zamena = [R2 == R, R3 == R, R4 == R, R5 == R, R6 == R, R7 == R]
```

```
zamena = (R2 = R R3 = R R4 = R R5 = R R6 = R R7 = R)
```

```
odziv.v3
```

```
ans =
- 
$$\frac{R_1 R_4 R_7 ug_1 - R_1 R_5 R_6 ug_2 + R_2 R_5 R_6 ug_1 + R_1 R_6 R_7 ug_1 - R_2 R_5 R_6 ug_2 + R_3 R_4 R_7 ug_1 - R_1 R_6 R_7 ug_2 + R_2 R_6 R_7 ug_1 - R_3 R_4 R_7 ug_2 - R_2 R_6 R_7 ug_2 + R_3 R_6 R_7 ug_1 - R_3 R_6 R_7 ug_2}{R_1 R_5 (R_4 + R_6)}$$

```

```
subs(odziv.v3, lhs(zamena), rhs(zamena))
```

subs

```
ans =
- 
$$\frac{4 R^3 ug_1 - 4 R^3 ug_2 + 2 R^2 R_1 ug_1 - 2 R^2 R_1 ug_2}{2 R^2 R_1}$$

```

simplify

```
v3Sol = simplify(subs(odziv.v3, lhs(zamena), rhs(zamena)))
```

```
v3Sol =
- 
$$\frac{(2 R + R_1) (ug_1 - ug_2)}{R_1}$$

```

# MATLAB: Symbolic Math Toolbox

```
syms T U t uR8(t) ug1(t) ug2(t)
assume(0 < U & 0 < T & 0 < t);
pobude = [ug1 == U * heaviside(t-T), ug2 == U * heaviside(t - 2*T)]
```

$pobude(t) = (ug_1(t) = U \text{heaviside}(t - T) \quad ug_2(t) = U \text{heaviside}(t - 2T))$

```
| subs(v3Sol, lhs(pobude), rhs(pobude))
```

```
ans =

$$\frac{(2R + R_1)(U \text{heaviside}(t - T) - U \text{heaviside}(t - 2T))}{R_1}$$

```

```
vrednosti = [U == sym(10), T == sym(1), R == sym(1000), R1 == sym(2000)]
```

$vrednosti = (U = 10 \quad T = 1 \quad R = 1000 \quad R_1 = 2000)$

```
uR8(t) = subs(subs(v3Sol, lhs(pobude), rhs(pobude)), lhs(vrednosti), rhs(vrednosti))
```

$uR8(t) = 20 \text{heaviside}(t - 2) - 20 \text{heaviside}(t - 1)$

```
ug1(t) = subs(subs(ug1, lhs(pobude), rhs(pobude)), lhs(vrednosti), rhs(vrednosti))
```

$ug1(t) = 10 \text{heaviside}(t - 1)$

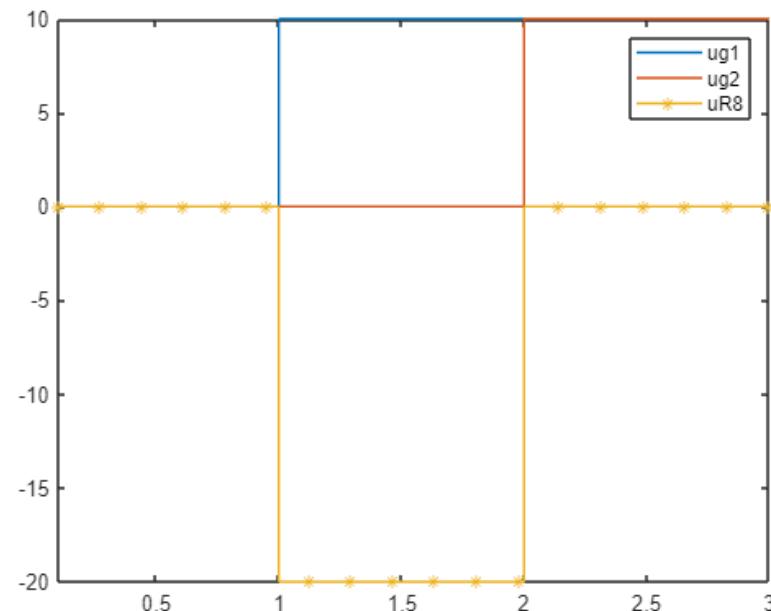
```
ug2(t) = subs(subs(ug2, lhs(pobude), rhs(pobude)), lhs(vrednosti), rhs(vrednosti))
```

$ug2(t) = 10 \text{heaviside}(t - 2)$

```
figure
fplot(ug1(t), [0.1, 3])
hold on
fplot(ug2(t), [0.1, 3])
fplot(uR8(t), [0.1, 3], '-*')
hold off
legend({'ug1', 'ug2', 'uR8'});
```

figure  
fplot

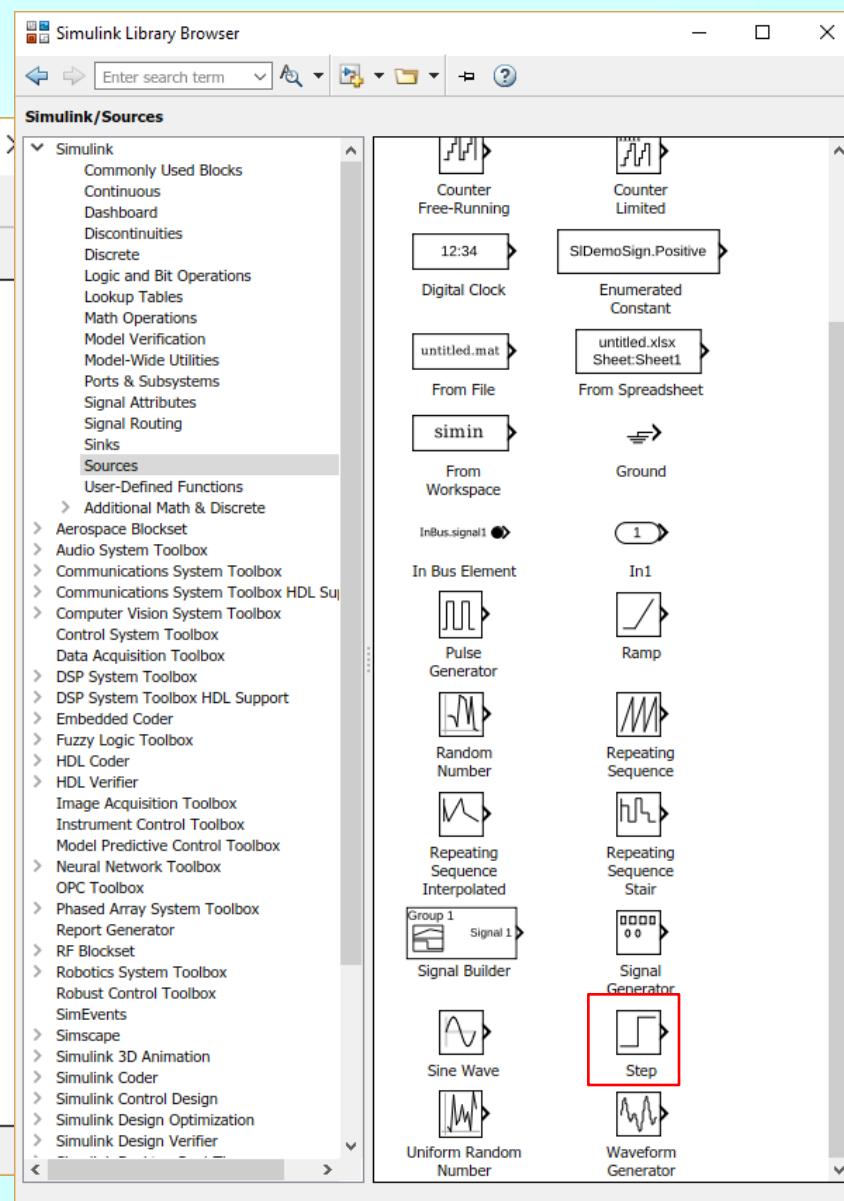
# График решења



```
pg = subs(jg1*ug1 + jg2*ug2, odziv)
```

$pg(t) = 0$

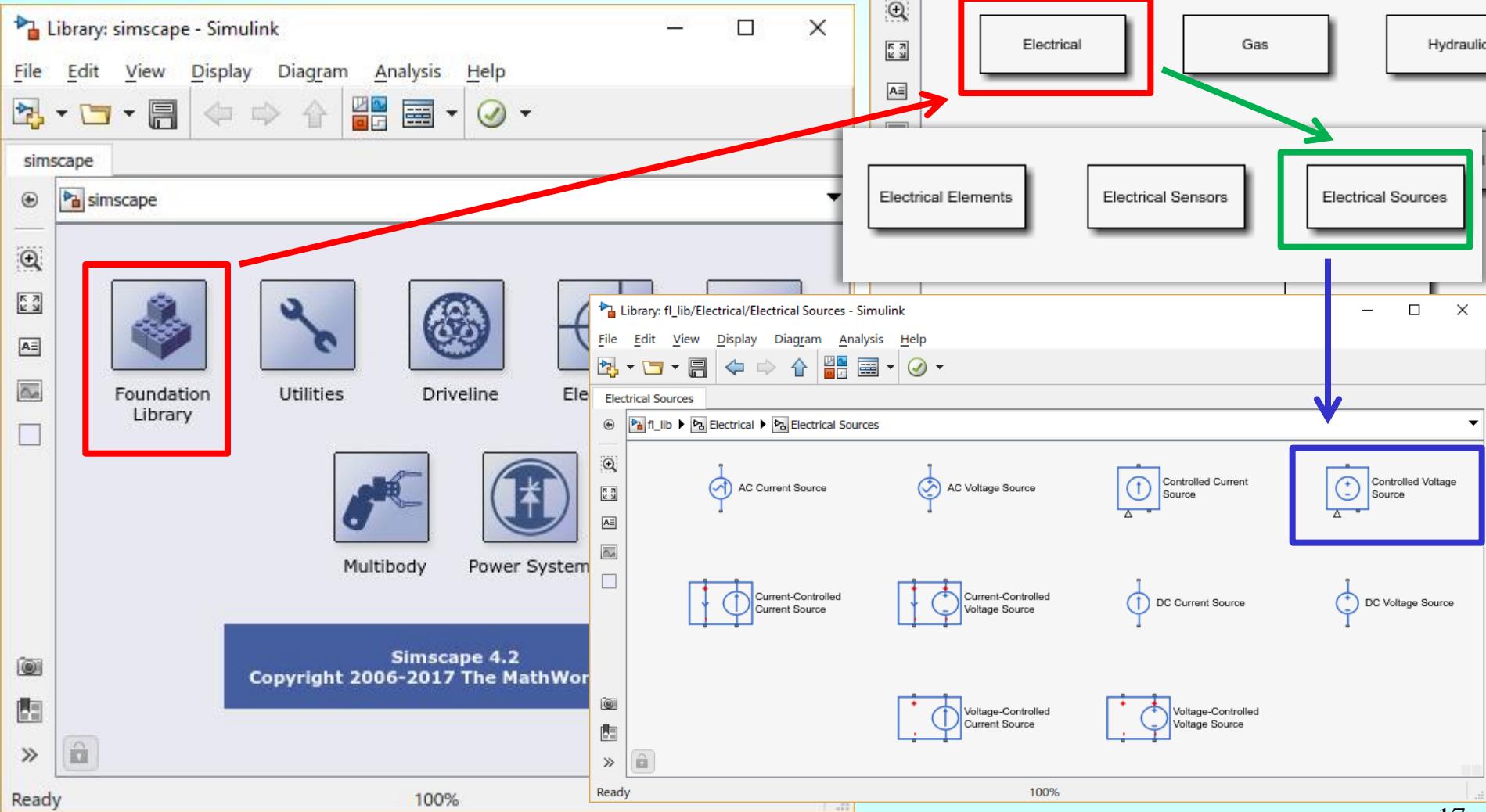
# MATLAB: Simulink Sources



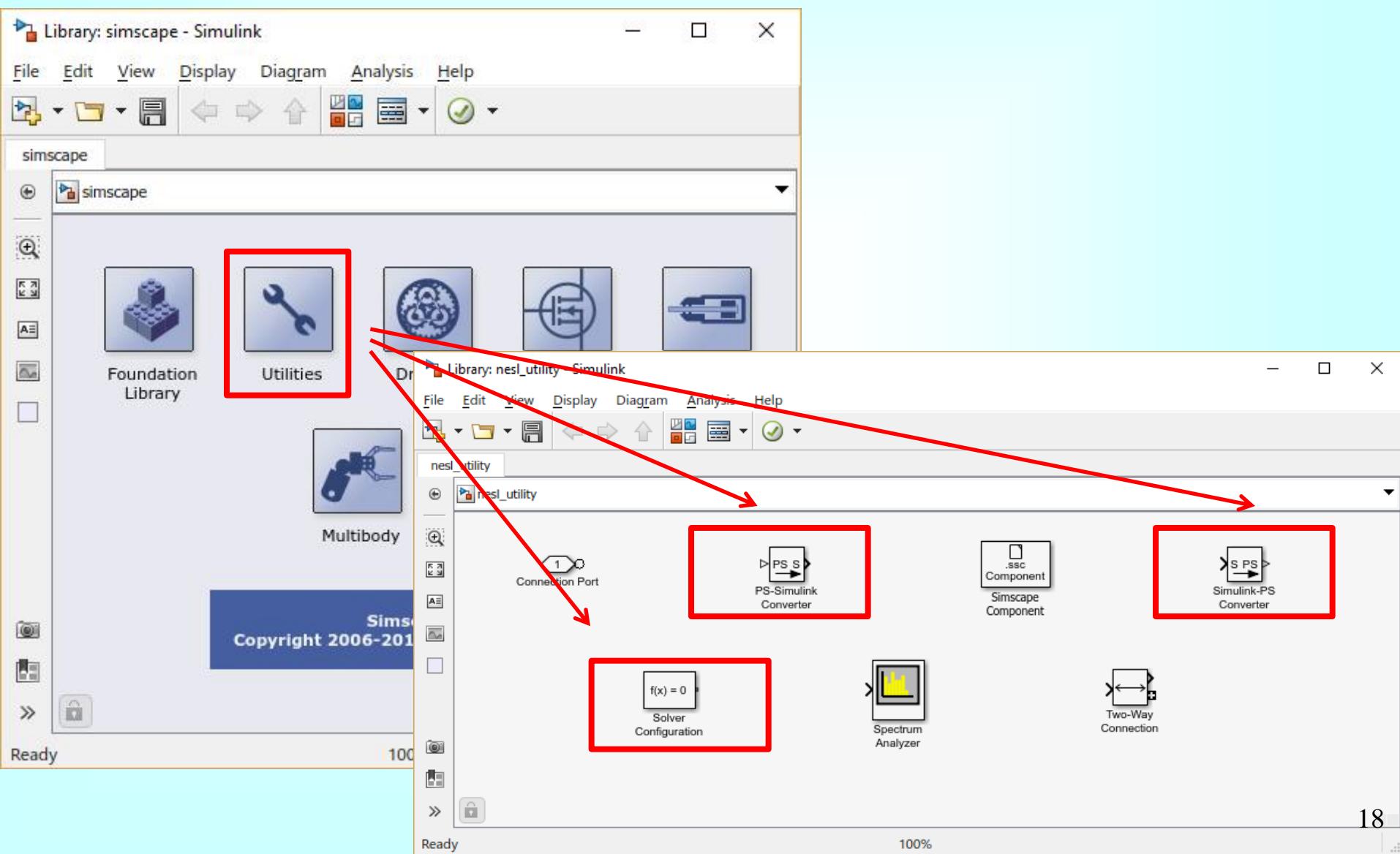
# MATLAB: Simscape

## Foundation Library

### Electrical, Electrical Sources

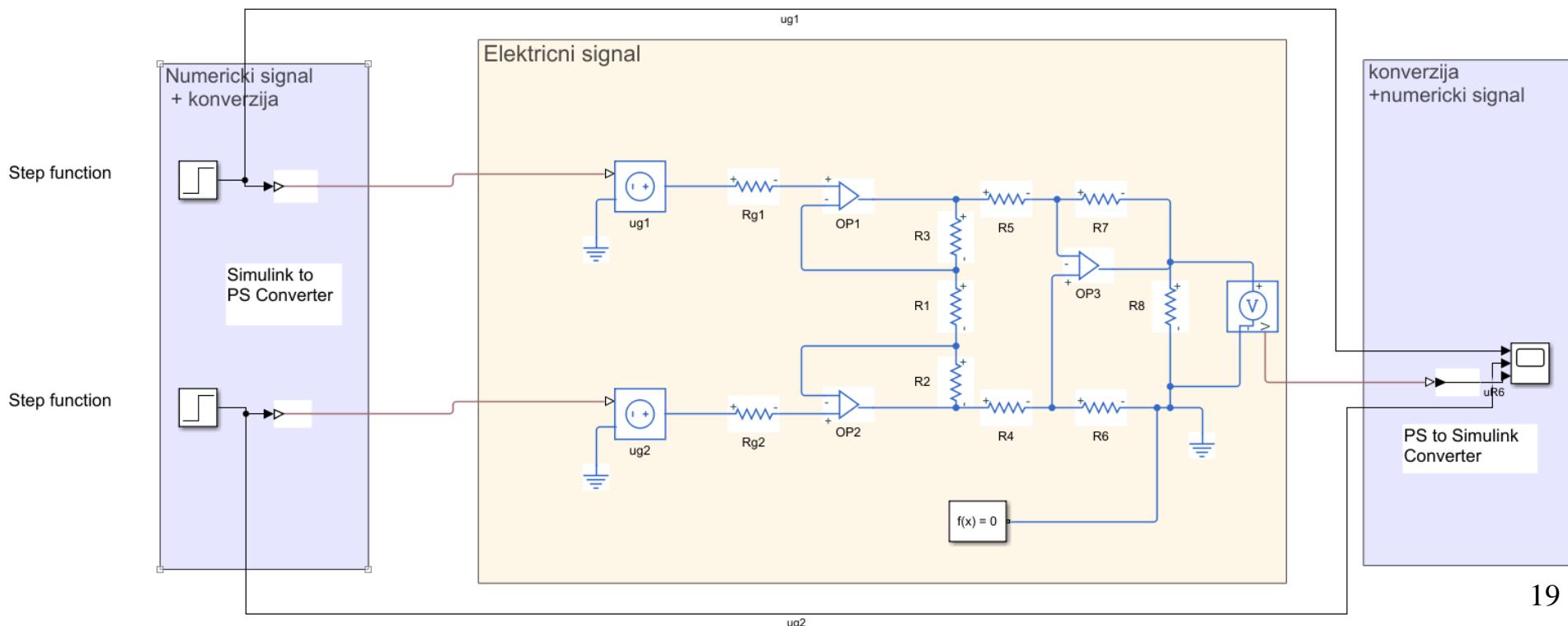
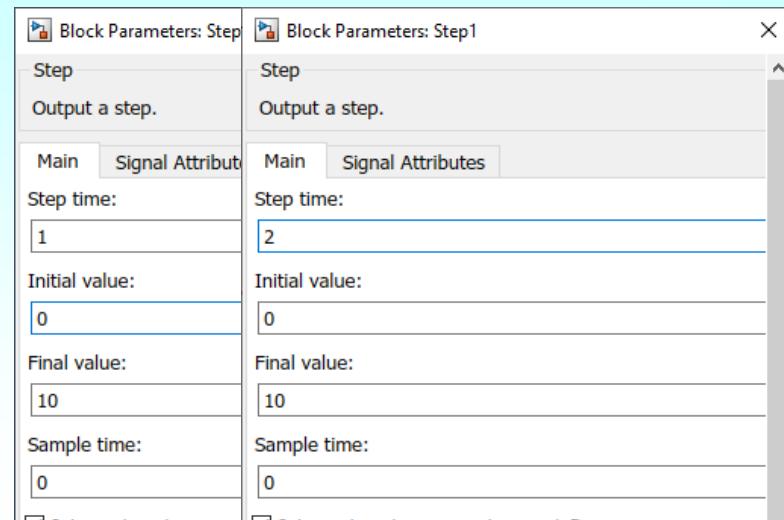


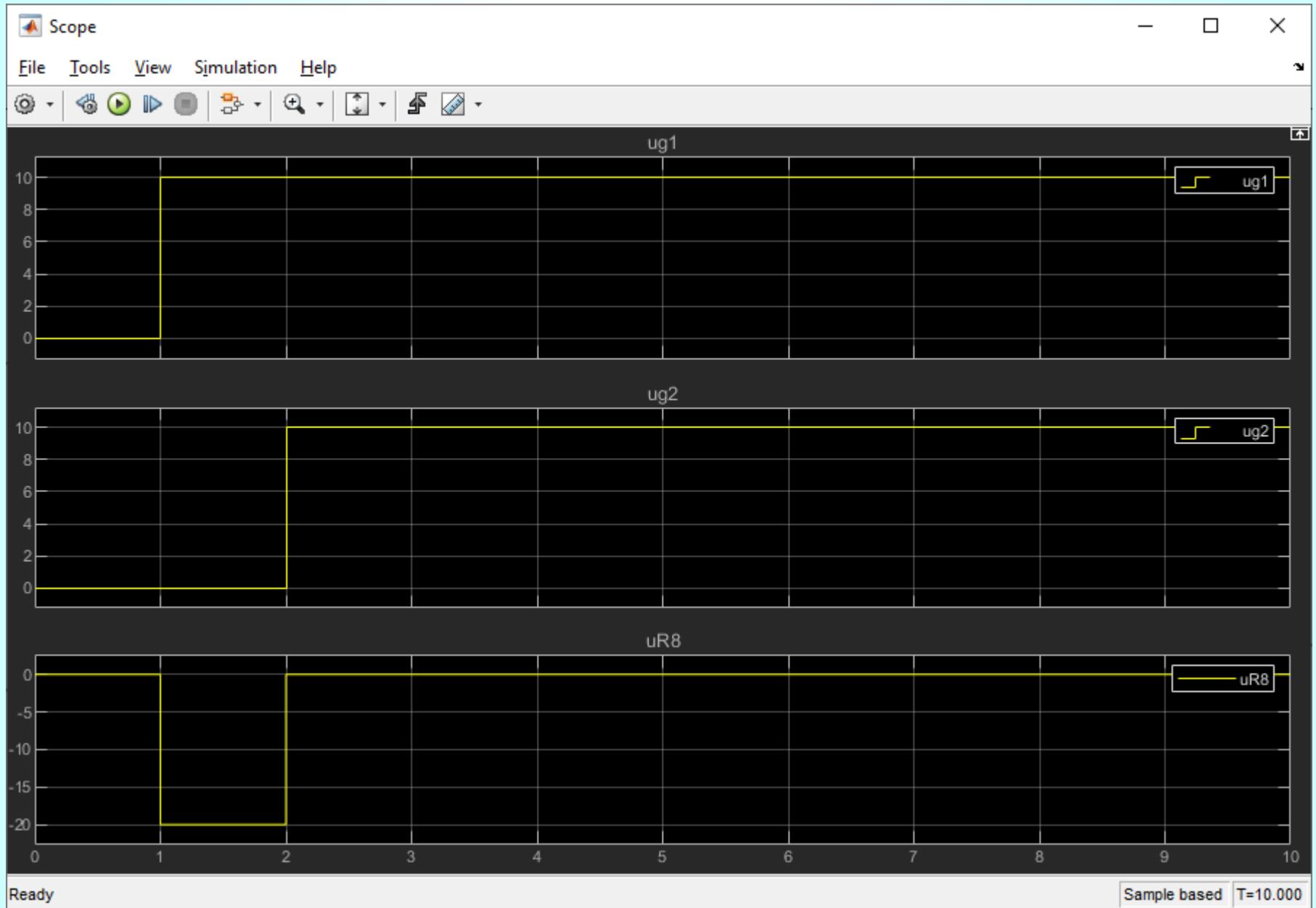
# MATLAB: Simscape Utilities



# MATLAB: Simscape

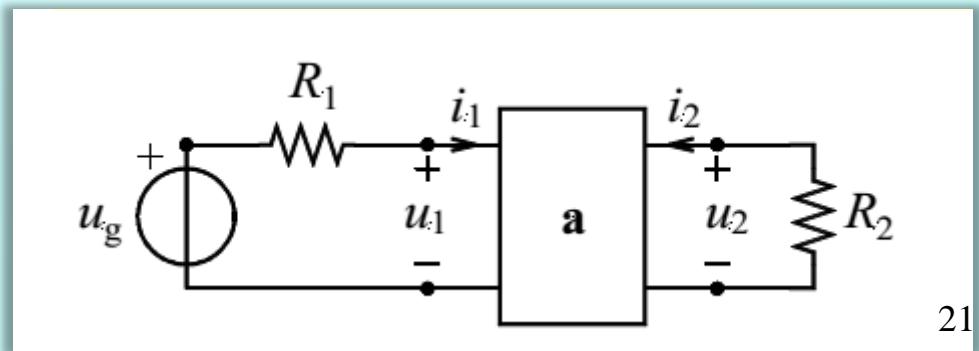
## Foundation Library, Utilities, Simulink





# ABCD параметри мреже

- Отпорности отпорника и  $a$ -параметри ( $ABCD$ -параметри) мреже са два приступа су познати.
- Одредити:
  - Количник напона  $A = u_2 / u_g$
  - Улазну отпорност мреже  $R_u = u_1 / i_1$
  - Струју  $i_1$
- Сматрати да су  $a$ -параметри мреже реални и различити од нуле.



```
clear all

syms R1 R2 a11 a12 a21 a22 i1 i2 u1 u2 ug
jednacine = [ug == R1 * i1 + u1, u2 + R2 * i2 == 0, u1 == a11 * u2 + a12 * -i2, i1 == a21 * u2 + a22 * -i2]

jednacine = (ug = u1 + R1 i1  u2 + R2 i2 = 0  u1 = a11 u2 - a12 i2  i1 = a21 u2 - a22 i2)

promenljive = [u1, u2, i1, i2]
promenljive = (i1  i2  u1  u2)

assume(a11*a22-a12*a21 ~= 0 & 0<R1 & 0<R2 & ug ~= 0);

odziv = solve(jednacine, promenljive)

odziv = struct with fields:
    i1: (a22*ug + R2*a21*ug)/(a12 + R2*a11 + R1*a22 + R1*R2*a21)
    i2: -ug/(a12 + R2*a11 + R1*a22 + R1*R2*a21)
    u1: (ug*(a12 + R2*a11))/(a12 + R2*a11 + R1*a22 + R1*R2*a21)
    u2: (R2*ug)/(a12 + R2*a11 + R1*a22 + R1*R2*a21)

odziv.i2

ans =
- 
$$\frac{ug}{a_{12} + R_2 a_{11} + R_1 a_{22} + R_1 R_2 a_{21}}$$


A = odziv.u2 / ug

A =

$$\frac{R_2}{a_{12} + R_2 a_{11} + R_1 a_{22} + R_1 R_2 a_{21}}$$

```

## MATLAB: Symbolic Math Toolbox